

TPP v.1.3.3.0 updated

05.04.2024

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- + **Added:** New algorithm for calculating calibration angles of lidar installation.
- + **Fixed:** length trimming works correctly for Hesai lidars.
- + **Added:** At group calculation of high-precision track 10 times less track points are displayed on maps (the program froze during rendering).
- + **Added:** In TopoSLAM, the return of the cloud to the track is accomplished by calibration.

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